## Standard ICs

## EL driver for portable sets <br> BA3899F

The BA3899F is an IC developed for EL drive applications. It uses a more compact interface than transformer systems, and is ideal for use in thin sets.

## - Applications

Pagers, electronic notebooks and other portable devices

## - Features

1) Drive oscillation frequency can be set using external capacitance.
2) Equipped with standby control pin.

- Absolute maximum ratings $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

| Parameter | Symbol | Limits | Unit |
| :--- | :---: | :---: | :---: |
| Power supply voltage | V cc | 8.0 | V |
| Power dissipation | Pd | $450^{*}$ | mW |
| Operating temperature | Topr | $-10 \sim+60$ | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature | Tstg | $-55 \sim+125$ | ${ }^{\circ} \mathrm{C}$ |
| Maximum applied voltage | V st | 8.0 | V |

* Reduced by 4.5 mW for each increase in Ta of $1^{\circ} \mathrm{C}$ over $25^{\circ} \mathrm{C}$.
- Recommended operating conditions ( $\mathrm{Ta}=25^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Power supply voltage | Vcc | 1.0 | 5.0 | 7.0 | V |

- Block diagram



## - Pin descriptions

| Pin No. | Pin name | $1 / 0$ | Pin voltage | Internal equivalent circuit | Function |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | GND | I | - | - | GND pin |
| 2 | N.C. | - | - | - | - |
| 3 | C1 | I/ O | - |  | OSC1 oscillator circuit; external capacitor pin |
| 4 | C2 | $1 / 0$ | - |  | OSC2 oscillator circuit; external capacitor pin |
| 5 | STBY | 1 | 0 |  | Standby control pin <br> (HIGH state: standby cancelled) <br> OWhen applying resistance, etc. to the STBY pin, be careful not to exceed the threshold values. |
| 6 | Vcc | I | - | - | Vcc input pin |
| 7 | SW2 | O | - |  | SW2 switching output pin |
| 8 | SW1 | O | - |  | SW1 switching output pin |

- Electrical characteristics (unless otherwise noted, $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{Vcc}=5.0 \mathrm{~V}, \mathrm{C} 1=0.033 \mu \mathrm{~F}, \mathrm{C} 2=1500 \mathrm{pF}$ )

| Parameter |  |  | Symbol | Min. | Typ. | Max. | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply current |  |  | Icc | 3.0 | 4.6 | 6.2 | mA | When used as stand-alone unit |
| C1 pin oscillation frequency |  |  | fsw1 | 75 | 95 | 120 | Hz | - |
| C2 pin oscillation frequency |  |  | fsw2 | 17 | 23 | 29 | kHz | - |
| SW1 | Source current |  | Iswiso | 100 | 140 | 180 | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{c} 1}=1.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{c} 2}=0.05 \mathrm{~V}, \mathrm{~V}_{\mathrm{sw}}=0 \mathrm{~V}$ |
|  | Sink current |  | Iswisı | -40 | - | - | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{c} 1}=0.05 \mathrm{~V}, \mathrm{~V}_{\mathrm{c} 2}=0.05 \mathrm{~V}, \mathrm{~V}_{\text {sw } 1}=1.0 \mathrm{~V}$ |
| SW2 | Source current |  | Isw2so | 3.2 | 4.4 | 6.1 | mA | $\mathrm{V}_{\mathrm{c} 1}=0.05 \mathrm{~V}, \mathrm{~V}_{\mathrm{c} 2}=0.05 \mathrm{~V}, \mathrm{~V}_{\text {sw }}=0 \mathrm{~V}$ |
|  | Pull-down resistance |  | Rsw2 | 400 | 500 | 600 | $\Omega$ | $\mathrm{Vst}=0.35 \mathrm{~V}, \mathrm{Vsw2}=0.3 \mathrm{~V}$ |
| Standby pin control voltage condition |  | Operating | Vston | 1.0 | - | - | V | - |
|  |  | Non-operating | Vstoff | - | - | 0.3 | V | - |
| Quiescent current in standby state |  |  | l (ST) | - | 0 | 2.0 | $\mu \mathrm{A}$ | - |

- Measurement circuit


Fig. 1

## - Application example



Fig. 2

* Because of the characteristics of the EL element, continuous application of particularly high DC power supply voltage can shorten the lifetime of the element. To avoid this, we recommend inserting a switch in the power supply line.


Fig. 3

## - Operation notes

(1) EL drive output

As shown in Figure 4, the EL drive output consists of charging (rise in voltage caused by switching) and discharging waveforms. The switching frequency is determined by fswz and the charging and discharging timing by fsw.
(4) Q1, Q2, and D1

The Vo (max.) shown in Figure 4 is applied to the output Vo, so if using any transistor other than that recommended, caution is required concerning the pressure withstand value. Also, Q2 must have characteristics which allow it to keep pace with the switching speed of fswz.

Fig. 4
(5) $R x$ (resistor for adjusting light volume)

With a configuration like that shown in Figure 5, the volume of light can be adjusted. However, Rx should be set so that Ix satisfies the following condition.

$$
\mathrm{Ix}\left(=\frac{\mathrm{Vx}-0.2 \mathrm{~V}}{\mathrm{Rx}}\right)<40 \mu \mathrm{~A}
$$

If $\mathrm{Ix}>40 \mu \mathrm{~A}$, LSI dispersion, temperature fluctuation, and other elements can cause oscillation of the C2 pin to stop. Be sure the above condition is satisfied.


Fig. 5

The recommended setting range for fsw 1 is 40 Hz to 800 Hz . However, the Vo (Max.) shown in Figure 4 is determined by fsw ${ }^{1}$, so caution is required concerning the pressure withstand values of Q1, Q2, and D1.
(3) fsw2
fswz is the switching pressure rise frequency, and is determined by the external capacitance of the C 2 pin. This value ( 1500 pF ) is determined by the inductance value and the Q2 transistor capability. When changing this value, the drive capability of Q2 must be taken into consideration in order to avoid the possibility of malfunction.

## - Electrical characteristic curves



Fig. 6 Supply current (when used as stand-alone unit) vs. power supply voltage


Fig. 8 SW1 sink current vs. power supply voltage


Fig. 10 SW2 source current vs. power supply voltage


Fig. 7 Oscillation frequency of C1 and C2 pins vs. power supply voltage


Fig. 9 SW1 source current vs. power supply voltage


Fig. 11 SW2 pull-down resistance vs. power supply voltage

- External dimensions (Units: mm)


